

8202A DYNAMIC RAM CONTROLLER

- Provides All Signals Necessary to Control 2104A, 2117, or 2118 Dynamic Memories
 - Directly Addresses and Drives Up to 128K Bytes Without External Drivers
 - Provides Address Multiplexing and Strobes
 - Provides a Refresh Timer and a Refresh Counter
 - Refresh Cycles May be Internally or Externally Requested
- Provides Transparent Refresh Capability
 - Fully Compatible with Intel® 8080A, 8085A, iAPX 88, and iAPX 86 Family Microprocessors
 - Decodes CPU Status for Advanced Read Capability
 - Provides System Acknowledge and Transfer Acknowledge Signals
 - External Clock Capability

The Intel® 8202A is a Dynamic Ram System Controller designed to provide all signals necessary to use 2104A, 2117, or 2118 Dynamic RAMs in microcomputer systems. The 8202A provides multiplexed addresses and address strobes, as well as refresh/access arbitration. Refresh cycles can be started internally or externally.

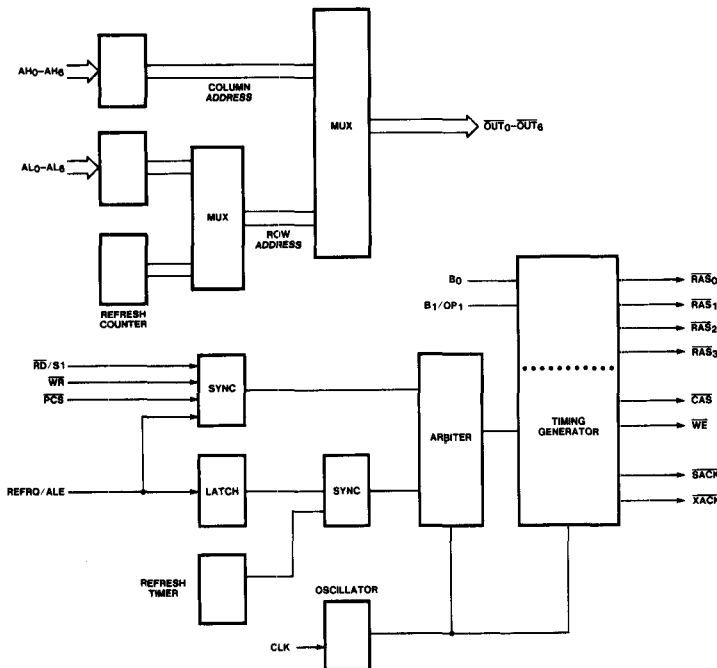


Figure 1. 8202A Block Diagram

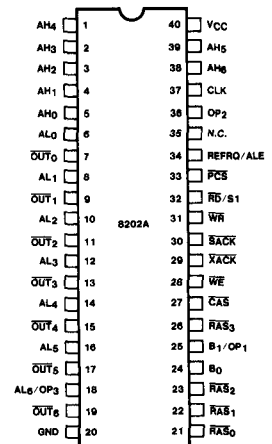


Figure 2. Pin Configuration

Table 1. Pin Descriptions

Symbol	Pin No.	Type	Name and Function
AL ₀	6	I	Address Low: CPU address inputs used to generate memory row address. AL ₆ /OP ₃ used to select 4K RAM mode.
AL ₁	8	I	
AL ₂	10	I	
AL ₃	12	I	
AL ₄	14	I	
AL ₅ AL ₆ / OP ₃	16 18	I	
AH ₀	5	I	Address High: CPU address inputs used to generate memory column address.
AH ₁	4	I	
AH ₂	3	I	
AH ₃	2	I	
AH ₄	1	I	
AH ₅ AH ₆	39 38	I	
BO B ₁ /OP ₁	24 25	1 1	Bank Select Inputs: Used to gate the appropriate RAS ₀ -RAS ₃ output for a memory cycle. B ₁ /OP ₁ option used to select the Advanced Read Mode.
PCS	33	I	Protected Chip Select: Used to enable the memory read and write inputs. Once a cycle is started, it will not abort even if PCS goes inactive before cycle completion.
WR	31	I	Memory Write Request.
RD/S1	32	I	Memory Read Request: S1 function used in Advanced Read mode selected by OP ₁ (pin 25).
REFRQ/ ALE	34	I	External Refresh Request: ALE function used in Advanced Read mode, selected by OP ₁ (pin 25).
OUT ₀ OUT ₁ OUT ₂ OUT ₃ OUT ₄ OUT ₅ OUT ₆	7 9 11 13 15 17 19	O O O O O O O	Output of the Multiplexer: These outputs are designed to drive the addresses of the Dynamic RAM array. For 4K RAM operation, OUT ₆ is designed to drive the 2104A CS input. (Note that the OUT ₀₋₆ pins do not require inverters or drivers for proper operation.)
WE	28	O	Write Enable: Drives the Write Enable inputs of the Dynamic RAM array.
CAS	27	O	Column Address Strobe: This output is used to latch the Column Address into the Dynamic RAM array.

Symbol	Pin No.	Type	Name and Function
RAS ₀ RAS ₁ RAS ₂ RAS ₃	21 22 23 26	O O O O	Row Address Strobe: Used to latch the Row Address into the bank of dynamic RAMs, selected by the 8202A Bank Select pins (B ₀ , B ₁ /OP ₁).
XACK	29	O	Transfer Acknowledge: This output is a strobe indicating valid data during a read cycle or data written during a write cycle. XACK can be used to latch valid data from the RAM array.
SACK	30	O	System Acknowledge: This output indicates the beginning of a memory access cycle. It can be used as an advanced transfer acknowledge to eliminate wait states. (Note: If a memory access request is made during a refresh cycle, SACK is delayed until XACK in the memory access cycle).
OP ₂ CLK	36 37	I I	Clock Inputs: These inputs are used to control the frequency of the 8202A. CLK is a TTL input for an external clock and OP ₂ must be strapped to +12V.
N.C.	35		Reserved for future use.
V _{CC}	40		Power Supply: +5V.
GND	20		Ground.

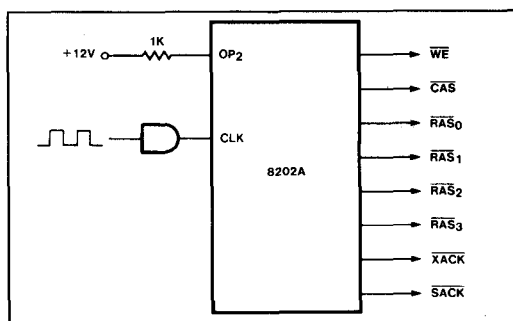


Figure 3. External Clock Operation

Functional Description

The 8202A provides a complete dynamic RAM controller for microprocessor systems as well as expansion memory

boards. All of the necessary control signals are provided for 2104A, 2117, and 2118 dynamic RAM's.

All 8202A timing is generated from a single reference clock. This clock is provided via an external oscillator. All output signal transitions are synchronous with respect to this clock reference, except for the CPU handshake signals SACK and XACK (trailing edge).

CPU memory requests normally use the \overline{RD} and \overline{WR} inputs. The advanced READ mode allows ALE and S1 to be used in place of the \overline{RD} input.

Failsafe refresh is provided via an internal refresh timer which generates internal refresh requests. Refresh requests can also be generated via the REFRQ input.

An on-chip synchronizer/arbiter prevents memory and refresh requests from affecting a cycle in progress. The READ, WRITE, and external REFRESH requests may be asynchronous to the 8202A clock; on-chip logic will synchronize the requests, and the arbiter will decide if the requests should be delayed, pending completion of a cycle in progress.

Option Selection

The 8202A has two hardware strapping options which can be selected by connecting the appropriate pin to a 12 volt power source through a current-limiting resistor. See "DC Characteristics" for more detail.

When OP₁ is selected, pin 32 changes from a \overline{RD} input to an S1 input, and pin 34 changes from a REFREQ input to an ALE input. See "Refresh Cycles" and "Read Cycles" for more detail.

When OP₃ is selected, the 8202A will change its internal refresh timer from 128-row refresh (2117, 2118) to 64-row refresh (2104A).

Refresh Timer

The refresh timer is used to monitor the time since the last refresh cycle occurred. When the appropriate amount of time has elapsed, the refresh timer will request a refresh cycle. External refresh requests will reset the refresh timer.

Refresh Counter

The refresh counter is used to sequentially refresh all of the memory's rows. The counter is incremented after every refresh cycle.

Address Multiplexer

The address multiplexer takes the address inputs and the refresh counter outputs, and gates them onto the address outputs at the appropriate time. The address outputs, in conjunction with the \overline{RAS}_0 – \overline{RAS}_3 and \overline{CAS} outputs, determine the address used by the dynamic RAMs for read, write, and refresh cycles. During the first part of a read or write cycle, AL₀–AL₆ are gated to \overline{OUT}_0 – \overline{OUT}_6 , then AH₀–AH₆ are gated to the address outputs.

During a refresh cycle, the refresh counter is gated onto the address outputs. All refresh cycles are RAS-only refresh (\overline{CAS} inactive, \overline{RAS}_0 – \overline{RAS}_3 active).

To minimize buffer delay, the information on the address outputs is inverted from that on the address inputs.

\overline{OUT}_0 – \overline{OUT}_6 do not need inverters or buffers unless additional drive is required beyond the 32 chip load.

Synchronizer/Arbiter

The 8202A has two inputs, \overline{RD} (pin 32) and \overline{WR} (pin 31), which allow an external CPU to request a memory read or write cycle, respectively. An additional input, REFRQ/ALE (pin 34), allows refresh requests to be requested external to the 8202A.

All three of these inputs may be asynchronous with respect to the 8202A's clock. The arbiter will resolve conflicts between refresh and memory requests, for both pending cycles and cycles in progress. Read and write requests will be given priority over refresh requests.

System Operation

The 8202A is always in one of the following states:

- a) IDLE
- b) TEST Cycle
- c) REFRESH Cycle
- d) READ Cycle
- e) WRITE Cycle

The 8202A is normally in the IDLE state. Whenever one of the other cycles is requested, the 8202A will leave the IDLE state to perform the desired cycle. If no other cycles are pending, the 8202A will return to the IDLE state.

Test Cycle

The TEST Cycle is used to check operation of several 8202A internal functions. TEST cycles are requested by activating the \overline{RD} and \overline{WR} inputs, independent of \overline{PCS} . The

Description	Pin #	Normal Function	+12 Volt Function
B1/OP1	25	Bank (RAS) Select	Advanced-Read Mode
AL6/OP3	18	Address Input	64-ROW Refresh

Figure 4. 8202A Option Selection

TEST Cycle will reset the refresh address counter and perform a WRITE Cycle. The TEST Cycle should not be used in normal system operation, since it would affect the dynamic RAM refresh.

Refresh Cycles

The 8202A has two ways of providing dynamic RAM refresh:

- 1) Internal (failsafe) refresh
- 2) External (hidden) refresh

Both types of 8202A refresh cycles activate all of the \overline{RAS} outputs, while \overline{CAS} , WE, \overline{SACK} , and \overline{XACK} remain inactive.

Internal refresh is generated by the on-chip refresh timer. The timer uses the 8202A clock to ensure that refresh of all rows of the dynamic RAM occurs every 2 milliseconds. If REFRQ is inactive, the refresh timer will request a refresh cycle every 10-16 microseconds.

External refresh is requested via the REFRQ input (pin 34). External refresh control is not available when the Advanced-Read mode is selected. External refresh requests are latched, then synchronized to the 8202A clock.

The arbiter will allow the refresh request to start a refresh cycle only if the 8202A is not in the middle of a cycle.

If a memory request and a refresh request reach the arbiter at the same time, the 8202A will honor the refresh request first. However, the external refresh synchronization takes longer than the memory request synchronization, so, relative to the 8202A input signals, a simultaneous memory request and external refresh request will result in the memory request being honored first. This 8202A characteristic can be used to "hide" refresh cycles during system operation. A circuit similar to Figure 5 can be used to decode the CPU's instruction fetch status to generate an external refresh request. The refresh request is latched while the 8202A performs the instruction fetch; the refresh cycle will start immediately after the memory cycle is completed, even if the \overline{RD} input has not gone inactive. If the CPU's instruction decode time is long enough, the 8202A can complete the refresh cycle before the next memory request is generated.

After each refresh cycle, the 8202A increments the refresh counter, reloads the refresh timer, and clears the external refresh latch. If the external refresh request is held active, the latch will be set again, and another refresh cycle will be generated. However, if a memory request is pending, it will be honored before the second refresh request. This feature prevents refresh from locking out memory request.

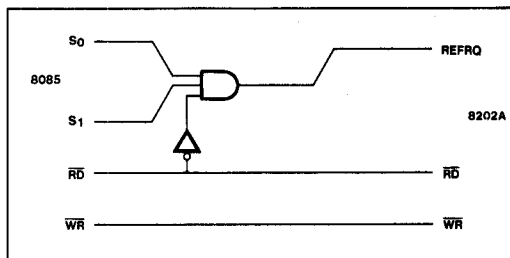


Figure 5. Hidden Refresh

Certain system configurations require complete external refresh requests. If external refresh is requested faster than the minimum internal refresh timer (t_{REF}), then, in effect, all refresh cycles will be caused by the external refresh request, and the internal refresh timer will never generate a refresh request.

Read Cycles

The 8202A can accept two different types of memory Read requests:

- 1) Normal Read, via the \overline{RD} input
- 2) Advanced Read, using the S1 and ALE inputs

The user can select the desired Read request configuration via the B1/OP1 hardware strapping option on pin 25.

	Normal Read	Advanced Read
Pin 25	B1 input	+12 Volt Option
Pin 32	RD input	S1 input
Pin 34	REFRQ input	ALE input
# RAM banks	4 (\overline{RAS} 0-3)	2 (\overline{RAS} 2-3)
Ext. Refresh	Yes	No

Figure 6. 8202A Read Options

Normal Reads are requested by activating the \overline{RD} input, and keeping it active until the 8202A responds with an \overline{XACK} pulse. The \overline{RD} input can go inactive as soon as the command hold time (t_{CHS}) is met.

Advanced Read cycles are requested by pulsing ALE while S1 is active; if S1 is inactive (low) ALE is ignored. Advanced Read timing is similar to Normal Read timing, except the falling edge of ALE is used as the cycle start reference.

If a Read cycle is requested while a refresh cycle is in progress, then the 8202A will set the internal delayed-SACK latch. When the Read cycle is eventually started, the 8202A will delay the active \overline{SACK} transition until \overline{XACK} goes active, as shown in the AC timing diagrams. This delay was designed to compensate for the CPU's READY

setup and hold times. The delayed-SACK latch is cleared after every READ cycle.

Based on system requirements, either \overline{SACK} or \overline{XACK} can be used to generate the CPU READY signal. \overline{XACK} will normally be used; if the CPU can tolerate an advanced READY, then \overline{SACK} can be used, but only if the CPU can tolerate the amount of advance provided by \overline{SACK} . If \overline{SACK} arrives too early to provide the appropriate number of WAIT states, then either \overline{XACK} or a delayed form of \overline{SACK} should be used.

Write Cycles

Write cycles are similar to Normal Read cycles, except for the \overline{WE} output. \overline{WE} is held inactive for Read cycles, but goes active for Write cycles. All 8202A Write cycles are "early-write" cycles; \overline{WE} goes active before \overline{CAS} goes active by an amount of time sufficient to keep the dynamic RAM output buffers turned off.

General System Considerations

All memory requests (Normal Reads, Advanced Reads, Writes) are qualified by the \overline{PCS} input. \overline{PCS} should be stable, either active or inactive, prior to the leading edge of \overline{RD} , \overline{WR} , or ALE. Systems which use battery backup should pullup \overline{PCS} to prevent erroneous memory requests, and should also pullup \overline{WR} to keep the 8202A out of its test mode.

In order to minimize propagation delay, the 8202A uses an inverting address multiplexer without latches. The system must provide adequate address setup and hold times to guarantee \overline{RAS} and \overline{CAS} setup and hold times for the RAM. The 8202A t_{AD} AC parameter should be used for this system calculation.

The B0-B1 inputs are similar to the address inputs in that they are not latched. B0 and B1 should not be changed during a memory cycle, since they directly control which \overline{RAS} output is activated.

The 8202A uses a two-stage synchronizer for the memory request inputs (\overline{RD} , \overline{WR} , ALE), and a separate two stage synchronizer for the external refresh input (REFRQ). As with any synchronizer, there is always a finite probability of metastable states inducing system errors. The 8202A synchronizer was designed to have a system error rate less than 1 memory cycle every three years based on the full operating range of the 8202A.

A microprocessor system is concerned with the time data is valid after \overline{RD} goes low. See Figure 7. In order to calculate memory read access times, the dynamic RAM's A.C. specifications must be examined, especially the RAS-access time (t_{RAC}) and the CAS-access time (t_{CAC}). Most configurations will be CAS-access limited; i.e., the data from the RAM will be stable $t_{cc,max}$ (8202A) + t_{CAC} (RAM) after a memory read cycle is started. Be sure to add any delays (due to buffers, data latches, etc.) to calculate the overall read access time.

Since the 8202A normally performs "early-write" cycles, the data must be stable at the RAM data inputs by the time \overline{CAS} goes active, including the RAM's data setup time. If the system does not normally guarantee sufficient write data setup, you must either delay the \overline{WR} input signal or delay the 8202A \overline{WE} output.

Delaying the \overline{WR} input will delay all 8202A timing, including the READY handshake signals, \overline{SACK} and \overline{XACK} , which may increase the number of WAIT states generated by the CPU.

If the \overline{WE} output is externally delayed beyond the \overline{CAS} active transition, then the RAM will use the falling edge of \overline{WE} to strobe the write data into the RAM. This \overline{WE} transition should not occur too late during the CAS active transition, or else the \overline{WE} to \overline{CAS} requirements of the RAM will not be met.

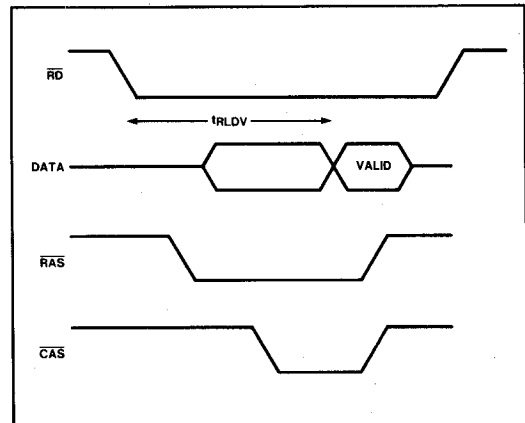


Figure 7. Read Access Time

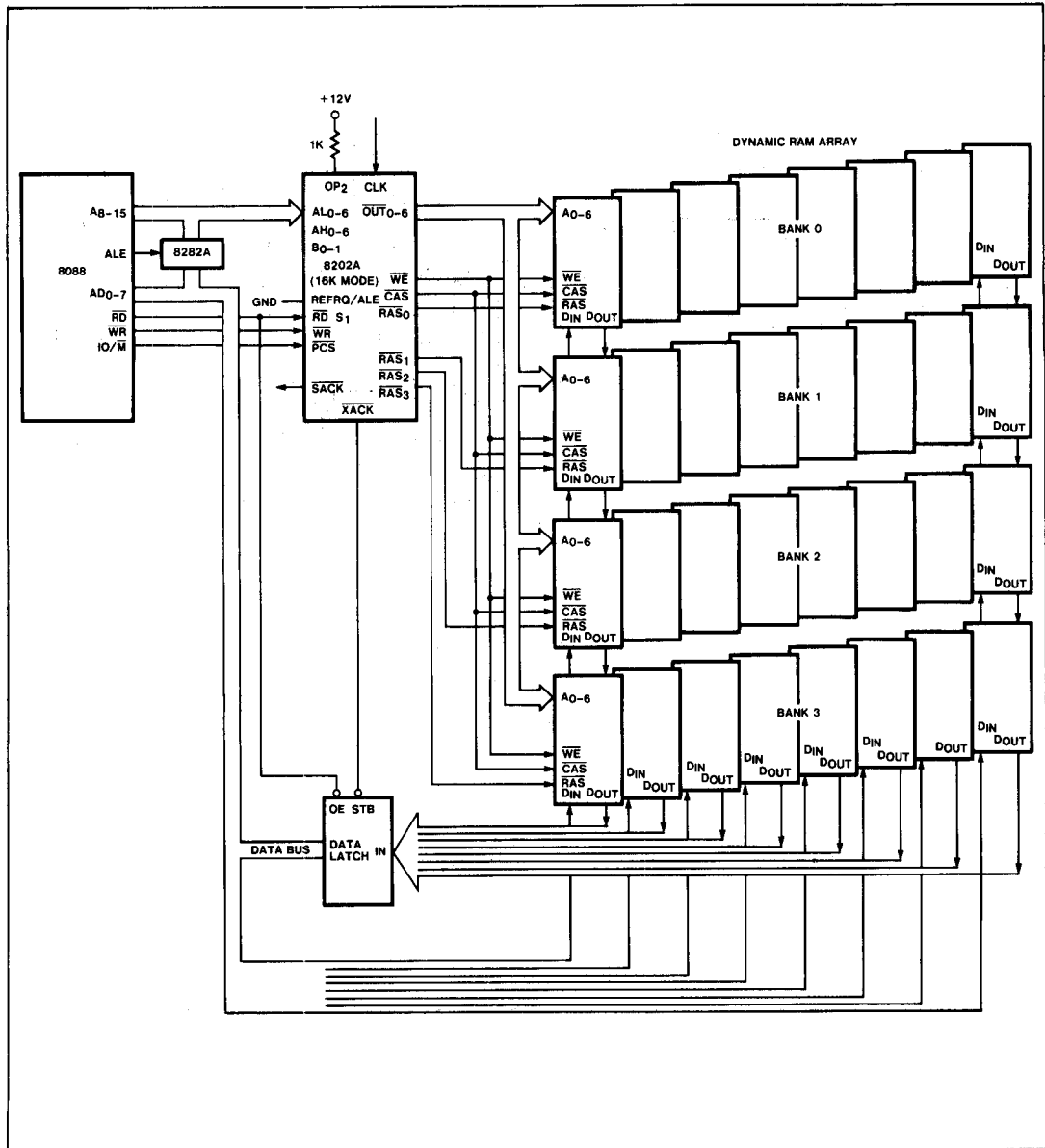


Figure 8. Typical 8088 System

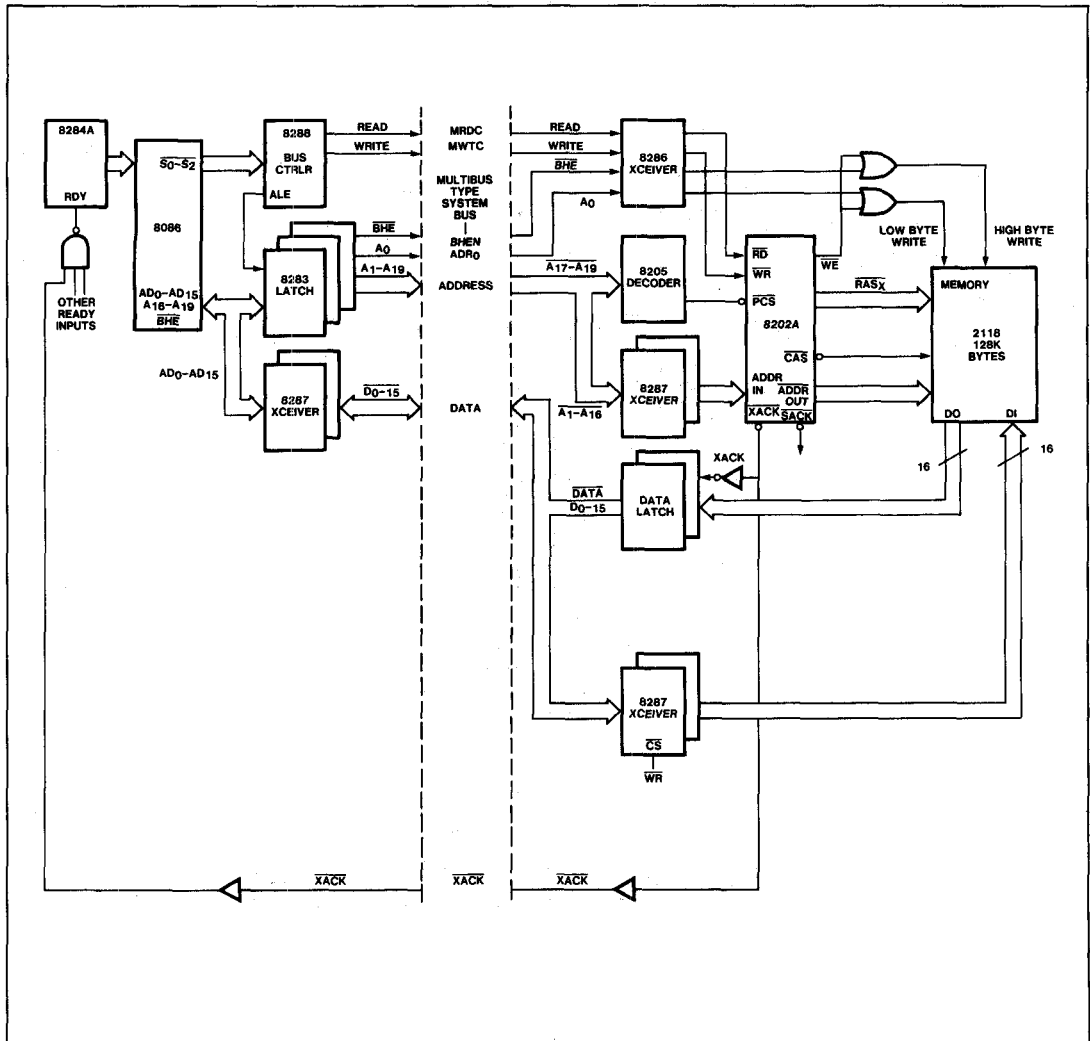


Figure 9. 8086/128K Byte System